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BE (4th Semester) Examination, Nov.-Dec., 2021

Branch : Et & T

SIGNALS AND SYSTESM (NEW)

Time Allowed : Three Hours Maximum Marks : 80 Minimum Pass Marks : 28

Note : (i) Part (a) is compulsory for every unit.

(ii) Attempt any two parts from (b), (c) & (d).

Unit-I

Q. 1. (a) Define causal & non-causal system with

example.

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(b) Check whether the given signals are energy

signal or power signal or neither : 7

(i)
$$x(t) = e^{-a|t|}$$
 for $a > 0$

(ii) $x(t) = e^{-5t} u(t)$

(c) (i) For the given signal x(t). Plot the

following wave forms :

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(1) x(2t)

(2) x(-t)

(3) x(t + 1)



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(ii) Draw even & odd components of x(n) : 4

$$x(n) = \{2, 4, 6, 8\}$$

(d) (i) Write the difference between energy & power signal.

(ii) If $y_1(t) \& y_2(t)$ are two periodic signals with two periods $T_1 \& T_2$ respectively. Find the suitable condition, so that $y(t) = y_1(t) + y_2(t)$ will be periodic. What

will be the fundamental period of y(t). 3

Unit-II

Q. 2. (a) Write Dirichlet condition for the existence of

Fourier series.

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(b) Find the trignometric Fourier series of full



(c) Write & prove any seven properties of

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Fourier transform.

(d) Find the Fourier transform of the following

signal :



(ii)
$$x(t) = A \cos w_0 t$$

(iii)
$$x(t) = A \sin w_0 t$$

Unit-III

Q. 3. (a) Write the condition for stability & causality of any discrete sequence h(n).

(b) Determine the z-transform of the following

signal & also plot its ROC.

$$x(n) = 2^{n}u(-n) + 3(\frac{1}{2})^{n}u(n)$$

(c) Find the inverse z-transform of x(z) using

partial fraction method :

$$\mathbf{x}(\mathbf{z}) = \frac{1 - \frac{1}{2}\mathbf{z}^{-1}}{\left(1 + \frac{3}{4}\mathbf{z}^{-1} + \frac{1}{8}\mathbf{z}^{-2}\right)}, \left|\mathbf{z}\right| > \frac{1}{2}$$

(d) Given an LTI system with system function :

(i)
$$H(z) = \frac{1}{(1 - 0.2z^{-1} + 0.4z^{-2} + 0.8z^{-3})}$$
 4

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(5)

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(ii)
$$H(z) = \frac{1}{(1 - \frac{1}{4}z^{-1})}$$

find difference equation for both.

Unit-IV

Q. 4. (a) Define transfer function.

(b) By using continuous time convolution integrals find out the response of the system to unit step input signal, impulse response is given by :

$$h(t) = \frac{R}{L} e^{-tR/L} u(t)$$

(c) A causal LTI discrete time system is described by the following difference equation :

$$y(n) = \frac{4}{5}y(n-1) + x(n)$$

Determine :

- (i) impulse response
- (ii) step response
- (iii) Is the system stable ?

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(d) Consider an LTI system with input x(n) &

impulse response h(n) given as : 7

$$x(n) = 2^{n} u(-n)$$

$$h(n) = u(n)$$

find the output of the system using convolution sum.

Unit-V

Q. 5. (a) Define state of the system.

(b) Consider the discrete time LTI system shown below in figure. Find the state space representation of the system by choosing the output of unit-delay element-1 and element-2 as state variable q₁[n] & q₂[n] respectively. 7



(c) Consider the RLC circuit shown in below figure. Let the output y(t) be the loop current. Find a state space representation of the 7 ckt.



(d) Find state equation of a discrete-time system described by : 7

0 [n] - 3/4 y [n-1] + 4/8 y [n-2] = 2 [n]

(8)

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